

# Rigid supersymmetric backgrounds of Newton-Cartan supergravity

James Liu

University of Michigan

13 April 2016

Knodel, Lisboa and JTL, [arXiv:1512.04961](https://arxiv.org/abs/1512.04961)

# Outline

- ▶ Introduction/Motivation
  - Coupling field theories to gravity
- ▶ Newton-Cartan gravity and supergravity
  - Three-dimensional  $\mathcal{N} = 2$  supergravity
- ▶ Rigid supersymmetric backgrounds
  - Maximally supersymmetric and 1/2 BPS
- ▶ Concluding remarks

# Relativistic field theories in curved backgrounds

- ▶ There is a natural procedure to couple relativistic field theory to a curved background

$$\eta_{\mu\nu} \rightarrow g_{\mu\nu}, \quad \partial_\mu \rightarrow \nabla_\mu$$

- ▶ Consider, for example

$$S = \int d^4x \left[ -\frac{1}{2} \eta^{\mu\nu} \partial_\mu \phi \partial_\nu \phi - \frac{1}{2} m^2 \phi^2 \right]$$

$$\Rightarrow S = \int \sqrt{-g} d^4x \left[ -\frac{1}{2} g^{\mu\nu} \partial_\mu \phi \partial_\nu \phi - \frac{1}{2} m^2 \phi^2 \right]$$

- ▶ Why is this useful?
  - Needed for theories with dynamical gravity
  - Natural means to investigate the Weyl anomaly under  $g_{\mu\nu} \rightarrow e^{2\sigma} g_{\mu\nu}$

## Fixing the curvature couplings

- ▶ But not all couplings are uniquely determined

$$S = \int \sqrt{-g} d^4x \left[ -\frac{1}{2} g^{\mu\nu} \partial_\mu \phi \partial_\nu \phi - \frac{1}{2} m^2 \phi^2 - \frac{1}{6} R \phi^2 \right]$$

- ▶ In some cases, the couplings are fixed by additional symmetries
  - minimal versus conformal coupling
  - comparison to string amplitudes (for effective string actions)
  - invariance under supersymmetry
- ▶ Many powerful results for supersymmetric field theories in a curved background
  - Supersymmetric partition functions ( $S^4$ ) and Wilson loops
  - The superconformal index ( $S^3 \times S^1$ )
  - Many supersymmetric observables can be computed using localization

## Rigid supersymmetric backgrounds

- ▶ How do we put a supersymmetric field theory in a curved background?
- ▶ Curved backgrounds are natural in supergravity theories
  - But we do not want dynamical gravity
- ▶ Take supergravity coupled to matter, and then freeze out gravity by taking  $M_{pl} \rightarrow \infty$ 
  - Decouple the gravitino, but demand  $\delta\psi_\mu = 0$
- ▶ This trick works best in an off-shell formalism with auxiliary fields
  - Gravitino variation does not include matter fields
  - There is no need to specify the supergravity equations of motion

[Festuccia and Seiberg, arXiv:1105.0689]

# Non-relativistic field theories and AdS/CMT

- ▶ Can we couple non-relativistic theories to a curved background?
- ▶ Recent interest motivated by non-relativistic holography

Lifshitz:  $ds^2 = -\frac{dt^2}{r^{2z}} + \frac{d\vec{x}^2 + dr^2}{r^2}$

Schrödinger:  $ds^2 = -\frac{dt^2}{r^{2z}} + \frac{2dt d\xi + d\vec{x}^2 + dr^2}{r^2}$

- ▶ We can perform a Wigner-Inönü contraction to obtain non-relativistic symmetry

Poincaré	→	Galilei
translations $P_\mu$		time translation $H$ space translation $P_i$
Lorentz $M_{\mu\nu}$		rotations $J_{ij}$ Galilean boosts $G_i$

# Coupling a Galilean theory to gravity

- ▶ Consider the free action [Son, arXiv:1306.0638]

$$S = \int dt d^d x \left[ \frac{i}{2} \Phi^\dagger \overleftrightarrow{D}_0 \Phi + \frac{\delta^{ij}}{2m} D_i \Phi^\dagger D_j \Phi \right]$$

Introduce a space metric  $h^{\mu\nu}$  and a velocity vector  $v^\mu$

$$S = \int d^{d+1} x \sqrt{\gamma} \left[ \frac{i}{2} v^\mu \Phi^\dagger \overleftrightarrow{D}_\mu \Phi + \frac{h^{\mu\nu}}{2m} D_\mu \Phi^\dagger D_\nu \Phi \right]$$

$$\gamma^{\mu\nu} = -v^\mu v^\nu + h^{\mu\nu}$$

- ▶ This can be made more systematic
  - ⇒ Newton-Cartan geometry
    - A reformulation of Newtonian gravity in a coordinate invariant manner
    - Can be obtained as a non-relativistic limit of general relativity

# Newton-Cartan gravity

- ▶ Take the  $c \rightarrow \infty$  limit of Einstein gravity

$$g_{\mu\nu} = \begin{pmatrix} c^2 g_{00} & c g_{0i} \\ c g_{i0} & g_{ij} \end{pmatrix} \rightarrow c^2 \begin{pmatrix} g_{00} & 0 \\ 0 & 0 \end{pmatrix} = c^2 \tau_{\mu\nu}$$
$$g^{\mu\nu} = \begin{pmatrix} g^{00}/c^2 & g^{0i}/c \\ g^{i0}/c & g^{ij} \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 0 \\ 0 & g^{ij} \end{pmatrix} = h^{\mu\nu}$$

- ▶ Writing the temporal metric as  $\tau_{\mu\nu} = \tau_\mu \tau_\nu$  with  $h^{\mu\nu} \tau_\nu = 0$  gives the Galilei structure  $(\mathcal{M}, \tau_\mu, h^{\mu\nu})$

$\tau_\mu$  : specifies time direction

$h^{\mu\nu}$  : (degenerate) spatial metric

- ▶ Introducing a vector  $v^\mu$  satisfying  $\tau_\mu v^\mu = 1$  gives the Newton-Cartan structure  $(\mathcal{M}, \tau_\mu, v^\mu, h^{\mu\nu})$

$v^\mu$  : velocity vector

## The central extension

- ▶ This now provides enough data to define a unique 'lower' metric  $h_{\mu\nu}$  satisfying

$$h_{\mu\nu} h^{\nu\rho} = \delta_{\mu}^{\rho} - \tau_{\mu} v^{\rho} \quad h_{\mu\nu} v^{\nu} = 0$$

(Note that  $h_{\mu\nu}$  and  $h^{\mu\nu}$  are not matrix inverses of each other, as they are not invertible)

- ▶ It is useful to extend the Galilei algebra to the Bargmann algebra by introducing

$$[G_i, P_j] = -\delta_{ij} M$$

where the central generator  $M$  is related to the mass

- ▶ Gauging  $M$  then introduces a  $U(1)$  current, and extends the Newton-Cartan structure to  $(\mathcal{M}, \tau_{\mu}, v^{\mu}, h^{\mu\nu}, m_{\mu})$

# Torsional Newton-Cartan geometry

- ▶ Motivated by holography we classify the Newton-Cartan geometries according to

$$d\tau = 0$$

Newton-Cartan (NC)

$$d\tau \neq 0 \text{ but } \tau \wedge d\tau = 0$$

twistless Newton-Cartan (TTNC)

$$\tau \wedge d\tau \neq 0$$

torsional Newton-Cartan (TNC)

[Christensen, Hartong, Obers and Rollier, arXiv:1311.4794]

- ▶ Here we focus only on the torsionless  $d\tau = 0$  case
  - We can introduce adapted coordinates by defining the time coordinate by  $\tau = dt$

$$\tau_\mu = (1, 0),$$

$$v^\mu = (1, v^i)$$

$$h^{\mu\nu} = \begin{pmatrix} 0 & 0 \\ 0 & h^{ij} \end{pmatrix},$$

$$h_{\mu\nu} = \begin{pmatrix} h_{kl} v^k v^l & -h_{jk} v^k \\ -h_{ik} v^k & h_{ij} \end{pmatrix}$$

where  $h_{ij} = (h^{ij})^{-1}$

## Working with adapted coordinates

- ▶ In the torsionless case, we can introduce a metric compatible connection

$$\nabla_{\mu} h^{\nu\lambda} = 0 \quad \nabla_{\mu} \tau_{\nu} = 0$$

where

$$\Gamma^{\rho}{}_{\mu\nu} = v^{\rho} \partial_{(\mu} \tau_{\nu)} + \frac{1}{2} h^{\rho\lambda} (\partial_{\nu} h_{\lambda\mu} + \partial_{\mu} h_{\lambda\nu} - \partial_{\lambda} h_{\mu\nu} + 2K_{\lambda(\mu} \tau_{\nu)})$$

$$K_{\mu\nu} = 2\partial_{[\mu} m_{\nu]}$$

- ▶ In the adapted coordinates, we find  $\Gamma^0{}_{\mu\nu} = 0$  along with

$$\Phi^i \equiv \Gamma^i{}_{00} = h^{ij} (\partial_i \varphi - \partial_0 A_j)$$

$$\Omega^i{}_j \equiv \Gamma^i{}_{0j} = \frac{1}{2} h^{ik} (\partial_0 h_{kj} + \partial_k A_j - \partial_j A_k)$$

$$\Gamma^i{}_{jk} = \frac{1}{2} h^{il} (\partial_j h_{lk} + \partial_k h_{lj} - \partial_l h_{jk})$$

where

$$\varphi = m_0 - \frac{1}{2} h_{ij} v^i v^j \quad A_i = m_i + h_{ij} v^j$$

[Andringa, Bergshoeff, Panda and de Roo, arXiv:1011.1145]

# Newtonian dynamics

- ▶ In adapted coordinates, the geodesic equation reduces to

$$\frac{d^2 x^i}{dt^2} + \Phi^i + 2\Omega^i_j \frac{dx^j}{dt} + \Gamma^i_{jk} \frac{dx^j}{dt} \frac{dx^k}{dt} = 0$$

- ▶ Newtonian gravity is obtained by taking the Einstein equation

$$R_{\mu\nu} = 4\pi G \rho \tau_\mu \tau_\nu$$

- The  $R_{ij} = 0$  component implies  $\Gamma^i_{jk} = 0$
- We can further make a coordinate transformation to set  $h^{ij} = \delta^{ij}$  and  $\Omega^i_j = 0$  so that

$$\frac{d^2 x^i}{dt^2} = -\partial_i \varphi \quad \text{along with} \quad R_{00} = \nabla^2 \varphi = 4\pi G \rho$$

where  $\Phi^i = \partial_i \varphi$

# Introduction of supersymmetry

- ▶ Can we supersymmetrize Newton-Cartan gravity?

Gauge a super-Bargmann algebra

symmetry	generator	gauge field
time translation	$H$	$\tau_\mu$
space translation	$P^a$	$e_\mu^a$
rotations	$J^{ab}$	$\omega_\mu^{ab}$
Galilean boosts	$G^a$	$\omega_\mu^a$
central charge	$M$	$m_\mu$
supersymmetries (3D)	$Q_\pm$	$\psi_{\mu\pm}$

- ▶ The on-shell 3-dimensional  $\mathcal{N} = 2$  theory was constructed in [Andringa, Bergshoeff, Rosseel and Sezgin, arXiv:1305.6737](#)

# Obtaining 3-dimensional Newton-Cartan supergravity

- ▶ We can also start from the relativistic theory and take the non-relativistic limit
  - Take the off-shell  $\mathcal{N} = (2, 0)$  theory [Howe, Izquierdo, Papadopoulos and Townsend, hep-th/9505032] as the starting point
  - Then perform a Wigner-Inönü contraction

vielbein	$E_\mu^A$	$\rightarrow$	$\tau_\mu,$	$e_\mu^a$
gravitini	$\Psi_{\mu i}$	$\rightarrow$	$\psi_{\mu\pm}$	
central charge gauge field	$M_\mu$	$\rightarrow$	$m_\mu$	
$R$ -charge gauge field	$V_\mu$			(eliminated)
auxiliary scalar	$D$	$\rightarrow$	$S$	

[Bergshoeff, Rosseel and Zojer, arXiv:1505.02095]

- ▶ This reproduces the on-shell result, but includes the auxiliary field  $S$

# The transformation rules

- ▶ The supersymmetry transformation rules

$$\delta\tau_\mu = \frac{1}{2}\bar{\epsilon}_+\gamma^0\psi_{\mu+}$$

$$\delta e_\mu^a = \frac{1}{2}(\bar{\epsilon}_+\gamma^a\psi_{\mu-} + \bar{\epsilon}_-\gamma^a\psi_{\mu+})$$

$$\delta m_\mu = \bar{\epsilon}_-\gamma^0\psi_{\mu-}$$

$$\delta\psi_{\mu+} = (D_\mu + S\tau_\mu\gamma_0)\epsilon_+$$

$$\delta\psi_{\mu-} = (D_\mu - 3S\tau_\mu\gamma_0)\epsilon_- + \left(\frac{1}{2}\omega_\mu^a\gamma_{a0} - S e_\mu^a\gamma_a\right)\epsilon_+$$

$$\delta S = -\frac{1}{8}\bar{\epsilon}_+\gamma^{a0}\hat{\psi}_{a0-}$$

- ▶ For a supersymmetric background, we set  $\psi_{\mu+} = \psi_{\mu-} = 0$ , and solve the Killing spinor equations  $\delta\psi_{\mu+} = \delta\psi_{\mu-} = 0$ 
  - Goal: obtain a solution for  $(\tau_\mu, e_\mu^a, m_\mu, S)$

# Integrability of the Killing spinor equation

- ▶ The Killing spinor equations are given by

$$D_\mu \epsilon_+ = -S \tau_\mu \gamma_0 \epsilon_+$$

$$D_\mu \epsilon_- = 3S \tau_\mu \gamma_0 \epsilon_- - \frac{1}{2} \omega_\mu^a \gamma_{a0} \epsilon_+ + S e_\mu^a \gamma_a \epsilon_+$$

- ▶ The integrability condition  $[D_\mu, D_\nu] \epsilon_\pm = 0$  then gives

$$A_{\mu\nu} \gamma_0 \epsilon_+ = 0$$

$$B_{\mu\nu} \gamma_0 \epsilon_- + C_{\mu\nu}^a \gamma_a \epsilon_+ = 0$$

where

$$A = -\frac{1}{4} R^{ab}(J) \epsilon_{ab} - \tau \wedge dS$$

$$B = -\frac{1}{4} R^{ab}(J) \epsilon_{ab} + 3\tau \wedge dS$$

$$C^a = -\frac{1}{2} \epsilon^a{}_b R^b(G) + e^a \wedge dS - 2S^2 \epsilon^a{}_b e^b \wedge \tau$$

# Supersymmetric backgrounds

- ▶ To obtain a supersymmetric background, we solve

$$A\gamma_0\epsilon_+ = 0$$

$$B\gamma_0\epsilon_- + C^a\gamma_a\epsilon_+ = 0$$

for  $\epsilon = (\epsilon_+, \epsilon_-)$  a four real component spinor

- ▶ We can consider the following cases

1. Maximally supersymmetric:

four independent Killing spinors  $\Rightarrow A = B = C^a = 0$

2. 1/2 BPS with  $\epsilon = (0, \epsilon_-) \Rightarrow B = 0$

3. 1/2 BPS with  $\epsilon = (\epsilon_+, 0) \Rightarrow A = C^a = 0$

4. 1/2 BPS with  $\epsilon = (\epsilon_+, F\epsilon_+)$  for some function  $F(x^\mu)$   
 $\Rightarrow A = 0$  with  $B$  and  $C^a$  related

# Maximal supersymmetry

- ▶ For maximal supersymmetry, we immediately obtain

$$\left. \begin{aligned} 0 = A &= -\frac{1}{4}R^{ab}(J)\epsilon_{ab} - \tau \wedge dS \\ 0 = B &= -\frac{1}{4}R^{ab}(J)\epsilon_{ab} + 3\tau \wedge dS \end{aligned} \right\} \Rightarrow R^{ab}(J) = 0, \quad \tau \wedge dS = 0$$

as well as

$$C^a = 0 \quad \Rightarrow \quad R^a(G) = -2\epsilon^a{}_b e^b \wedge dS - 4S^2 e^a \wedge \tau$$

- ▶ The curvature in terms of rotation and boost spin connections can be combined to give Riemann in terms of the (non-relativistic) Christoffel connection

$$R^\mu{}_{\nu\rho\sigma}(\Gamma) = -8S^2 \tau_\nu \tau_{[\rho} \delta^\mu_{\sigma]} + 4\epsilon^a{}_b e_a^\mu \tau_\nu e_{[\rho}^b \partial_{\sigma]} S$$

- ▶ Contracting gives  $R_{\mu\nu} = 8S^2 \tau_\mu \tau_\nu$ 
  - Newtonian dynamics with  $S^2$  playing the role of mass density (but we have not imposed any equations of motion)

# Maximal supersymmetry

- ▶ Supersymmetry imposes more than just the  $R_{\mu\nu}$  equation
- ▶ Working in a frame with  $h^{ij} = \delta^{ij}$  along with  $\Gamma^i{}_{00} = \partial_i\varphi$  and  $\Gamma^i{}_{0j} = 0$  gives

$$\partial_i\partial_j\varphi = 4S^2\delta_{ij} \quad \text{and} \quad S = \text{const.}$$

- ▶ This is solved by taking the Newtonian potential

$$\varphi(t, x^i) = 2S^2|x^i - \alpha^i(t)|^2 + \beta(t)$$

which is just a harmonic oscillator potential

- ‘Newtonian cosmology’ with a uniform background mass density

## Half-BPS with $\epsilon = (0, \epsilon_-)$

- ▶ For  $\epsilon_+ = 0$  we have a single Killing spinor equation

$$(D_\mu - 3S\tau_\mu\gamma_0)\epsilon_- = 0 \quad \Rightarrow \quad R^{ab}(J) = 6\epsilon^{ab}\tau \wedge dS$$

- ▶ In adapted coordinates, this again implies  $R_{ij} = 0$ , so we may choose  $h^{ij} = \delta^{ij}$

- This time, however, we have  $R_{0i}(\Gamma) = -6\epsilon_{ij}\partial_j S$ , which allows for a larger family of solutions

- ▶ We can choose arbitrary  $\Phi_i = \Gamma^i_{00}$  and  $\Omega = \frac{1}{2}\epsilon_{ij}\Gamma^i_{0j}$  along with  $S = \Omega/6 + f(t)$

- ▶ The Killing spinor is then

$$\epsilon_+ = 0 \quad \epsilon_- = e^{3\gamma_0 \int f(t) dt} \epsilon_0$$

- Note that this enhances to maximal supersymmetry when  $S = \text{const.}$

## Half-BPS with $\epsilon = (\epsilon_+, 0)$

- ▶ In this case, we have

$$\begin{aligned}(D_\mu + S\tau_\mu\gamma_0)\epsilon_+ &= 0 & \Rightarrow & & R^{ab}(J) &= -2\epsilon^{ab}\tau \wedge dS \\ (\frac{1}{2}\omega_\mu^a\gamma_{a0} - Se_\mu^a\gamma_a)\epsilon_+ &= 0\end{aligned}$$

- ▶ The first equation again gives  $R_{ij} = 0$  (so we choose  $h^{ij} = \delta^{ij}$ )
- ▶ Solving the algebraic equation then gives (in adapted coordinates)

$$\begin{aligned}S &= -\frac{1}{2}\Omega + \frac{1}{4}\epsilon^{ab}\partial_a v_b \\ \partial_{(a}v_{b)} &= 0 \\ \partial_a m_0 - \partial_0 m_a &= -\epsilon_{ab}v^b\epsilon^{cd}\partial_c m_d\end{aligned}$$

- ▶ The Killing spinor is

$$\epsilon_+ = e^{-\frac{1}{4}\gamma_0 \int \epsilon^{ab}\partial_a v_b dt} \epsilon_{0+}, \quad \epsilon_- = 0$$

## The general half-BPS case

- ▶ For a solution of the form  $(\epsilon_+, F\epsilon_+)$  we return to the Killing spinor equations

$$\begin{aligned}(D_\mu + S\tau_\mu\gamma_0)\epsilon_+ &= 0 &\Rightarrow & R^{ab}(J) = -2\epsilon^{ab}\tau \wedge dS \\ (D_\mu - 3S\tau_\mu\gamma_0)\epsilon_- &= -\left(\frac{1}{2}\omega_\mu^a\gamma_{a0} - Se_\mu^a\gamma_a\right)\epsilon_+\end{aligned}$$

- ▶ As before, we solve the first equation by writing  $h^{ij} = \delta^{ij}$  and taking  $\partial_i(S + \frac{1}{2}\Omega) = 0$
- ▶ The Killing spinor  $\epsilon_+$  is given by

$$\epsilon_+ = e^{-\gamma_0 \int (S + \frac{1}{2}C) dt} \epsilon_0$$

while  $\epsilon_-$  may be obtained by solving the inhomogeneous equation

- This gives additional constraints on the background

# What have we learned?

- ▶ In all cases, non-relativistic supersymmetry demands

$$R_{ij} = 0 \quad \Rightarrow \quad h^{ij} = \delta^{ij}$$

- Is this special to  $2 + 1$  dimensions, or does it also generalize to higher dimensions?
  - This is compatible with the Newtonian result  $R_{\mu\nu} = 4\pi G \rho \tau_\mu \tau_\nu$ , but we have not imposed any equations of motion
- ▶ This seems to forbid non-relativistic curved backgrounds such as  $S^1 \times S^2$ 
    - In the relativistic case, such rigid supersymmetric backgrounds are obtained by turning on a vector auxiliary field in the time direction
    - Here we have  $m_\mu$ , but it only enters indirectly through the connection

## Next steps

- ▶ Couple matter multiplets to Newton-Cartan supergravity and take the rigid limit to obtain non-relativistic supersymmetric field theories
- ▶ Extend Newton-Cartan supergravity to higher dimensions  
[Bergshoeff et al]
- ▶ Framework for describing non-relativistic scale anomalies

$$\langle zT_t^t + T_i^i \rangle \neq 0$$

- ▶ Develop (torsional) Newton-Cartan geometry as a framework for Lifshitz or Schrödinger holography